

Fig. 1

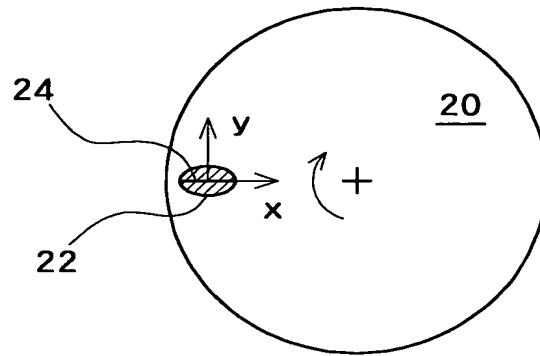


Fig. 2

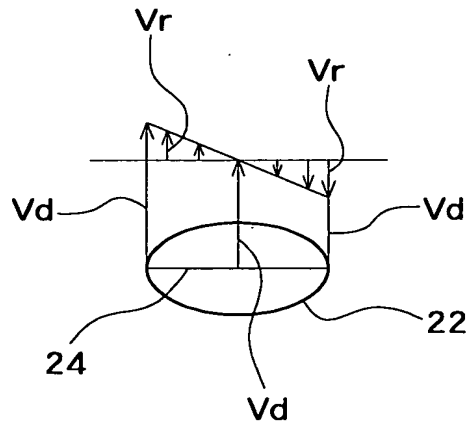


Fig. 3

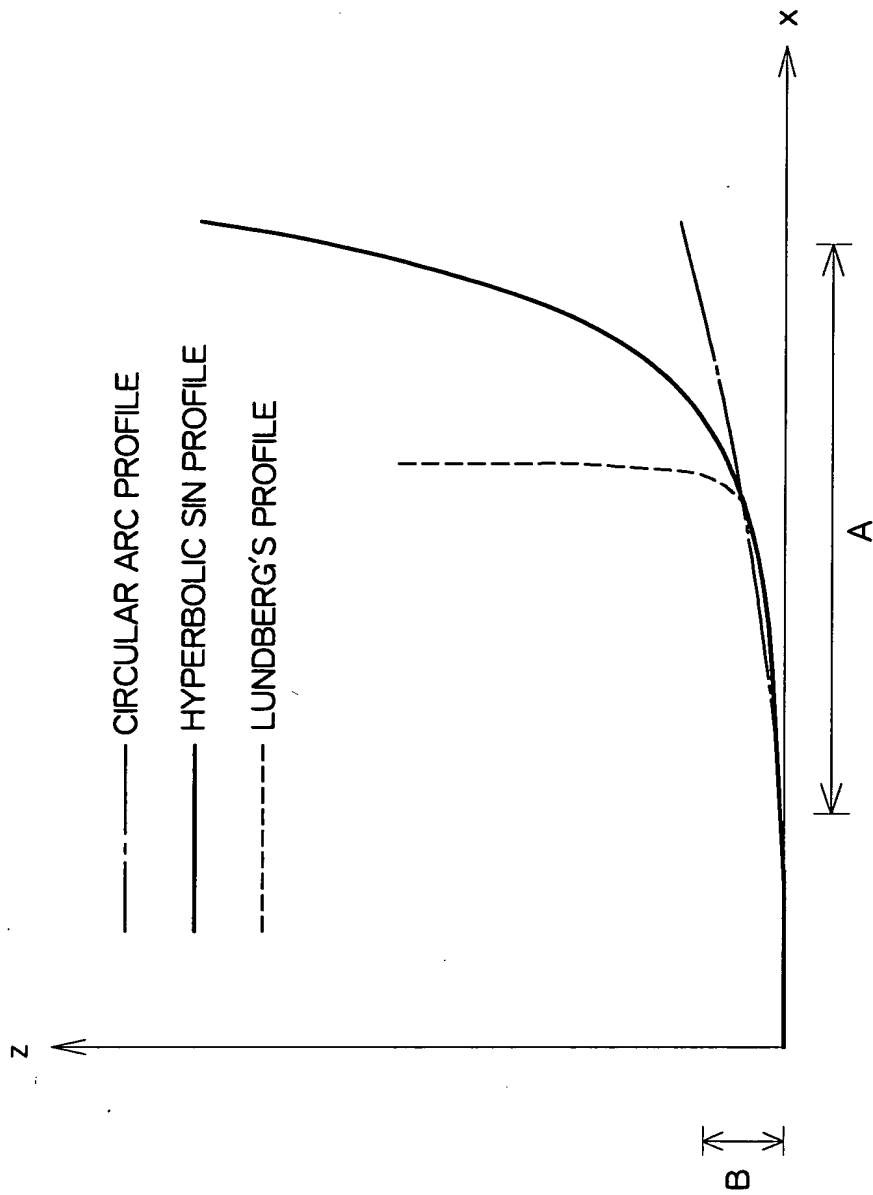


Fig.4

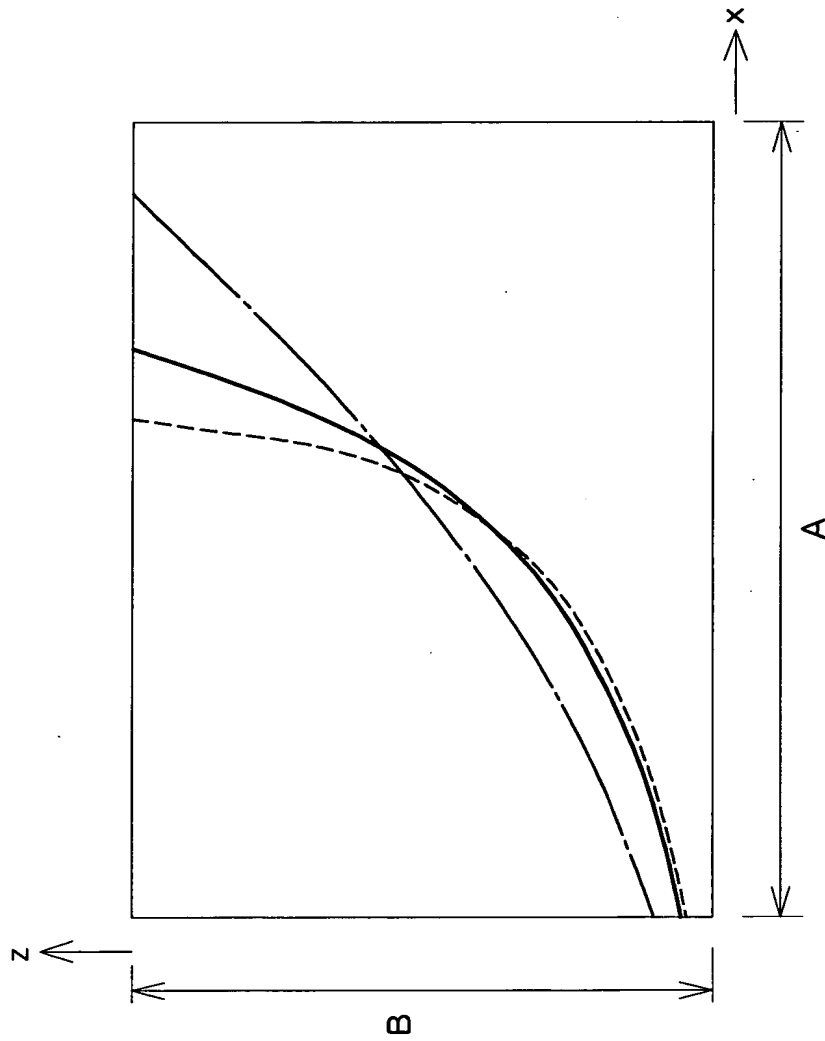


Fig.5

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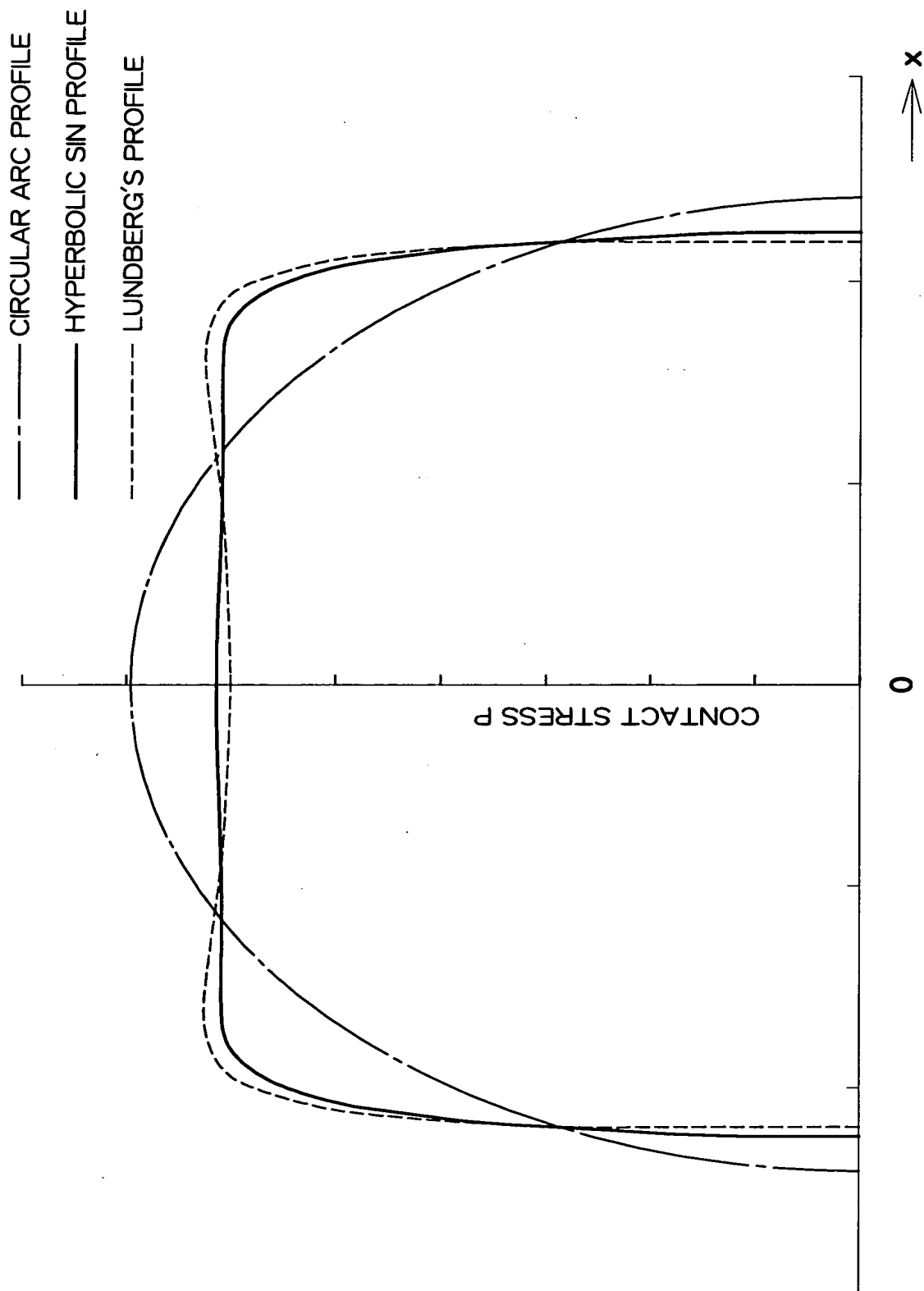


Fig.6

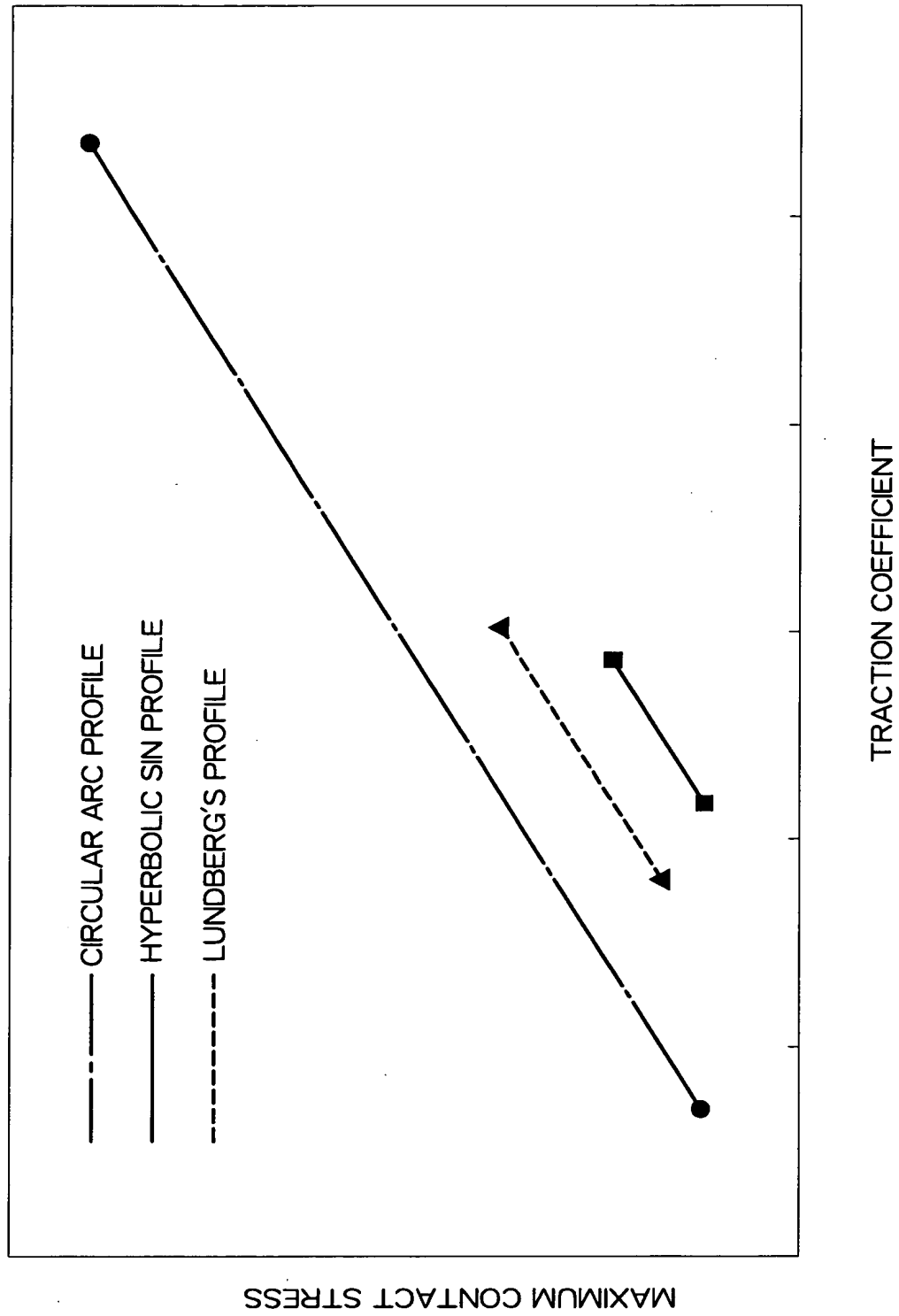


Fig.7

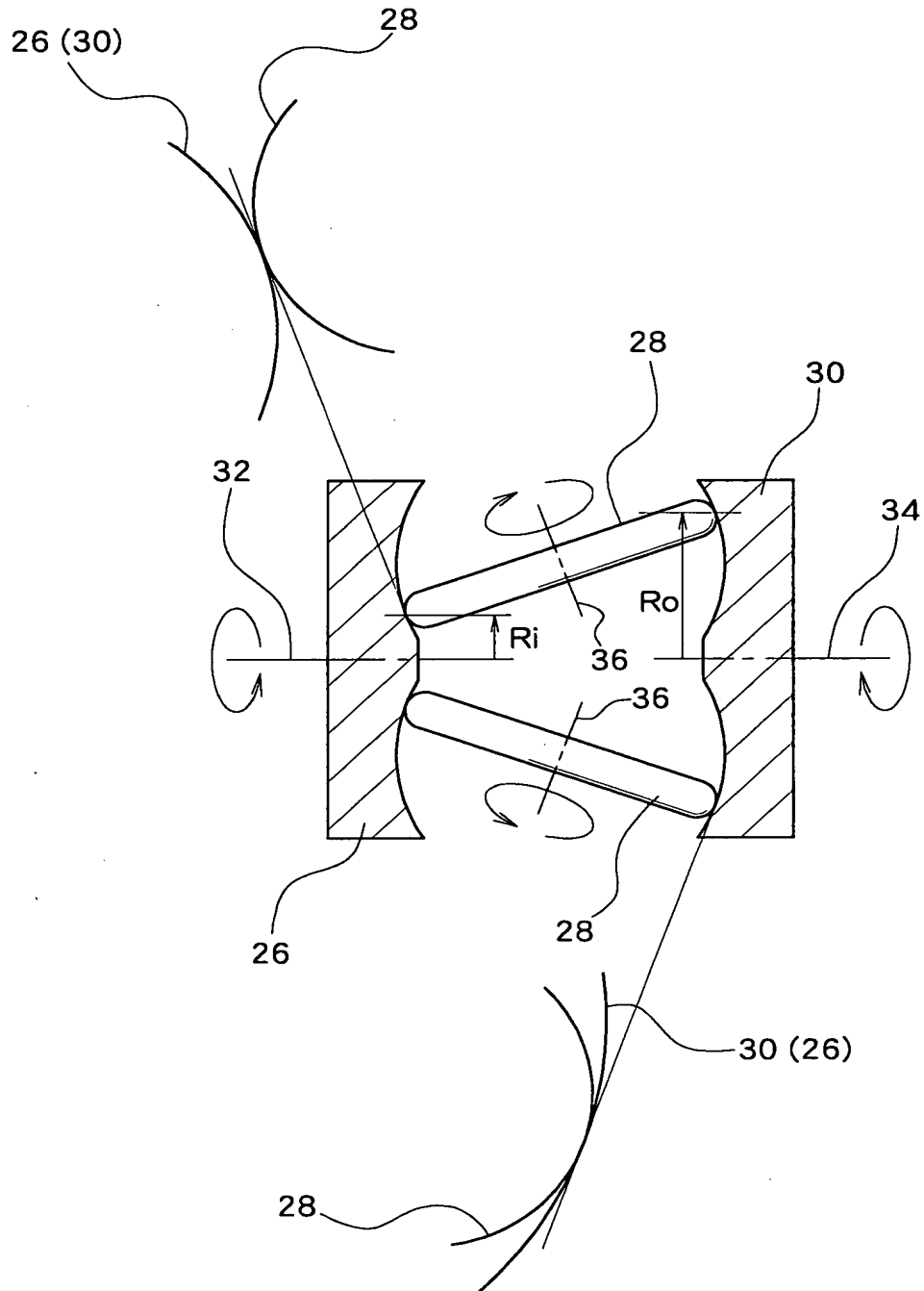


Fig.8

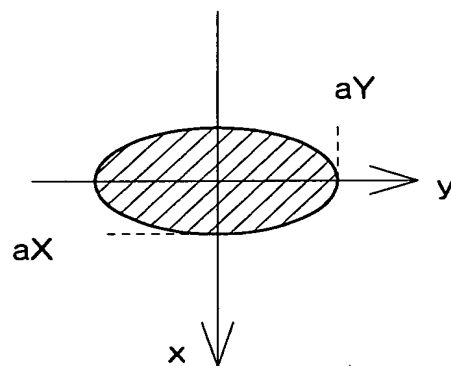


Fig.9

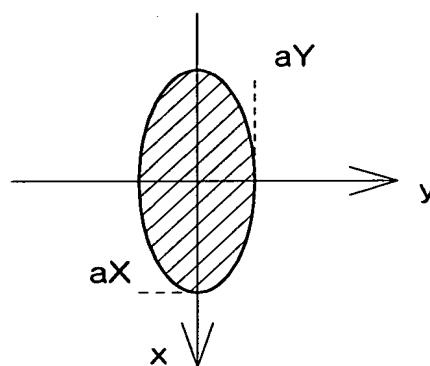


Fig.10

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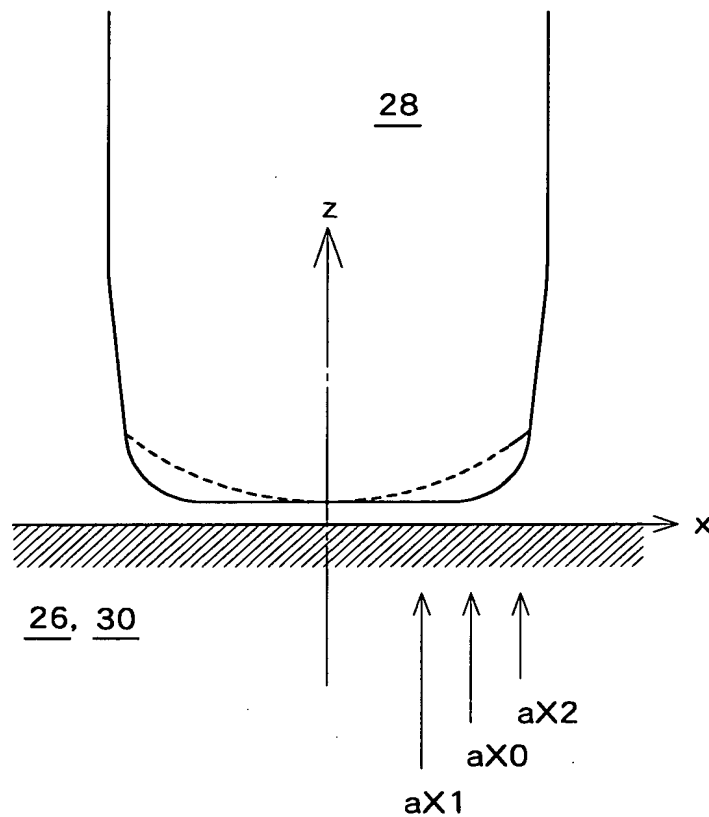
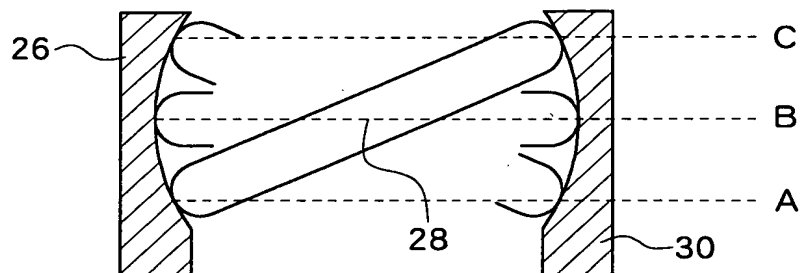


Fig.11







SPEED CHANGING STATE	INPUT CONTACT	OUTPUT CONTACT
DECELERATION	A	C
CONSISTENT SPEED	B	B
ACCELERATION	C	A

Fig.15

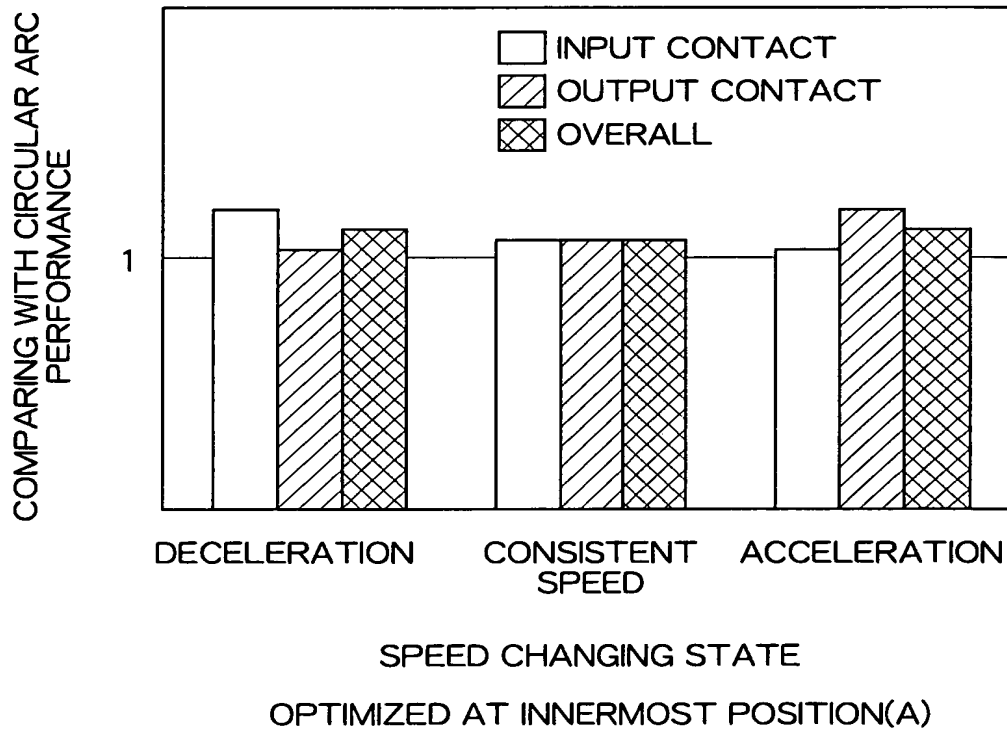
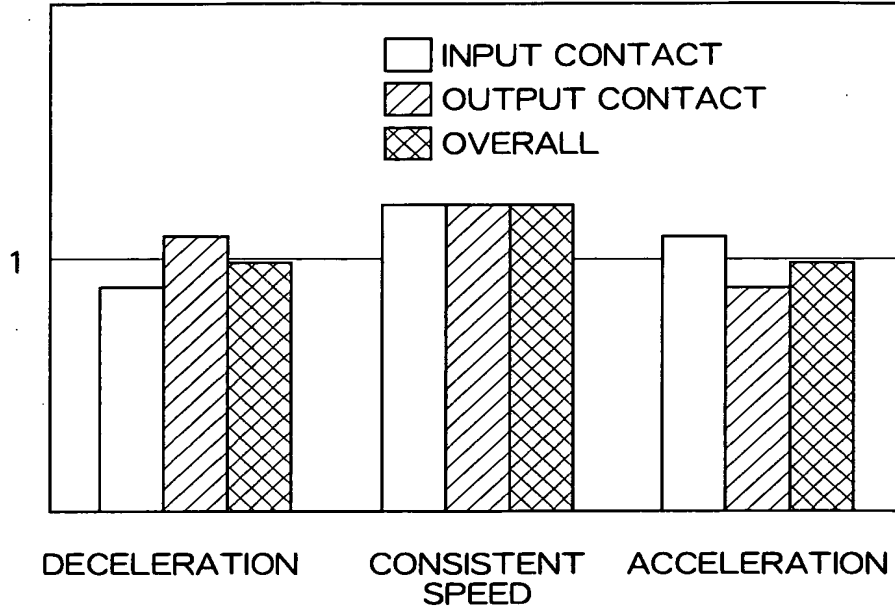


Fig.16

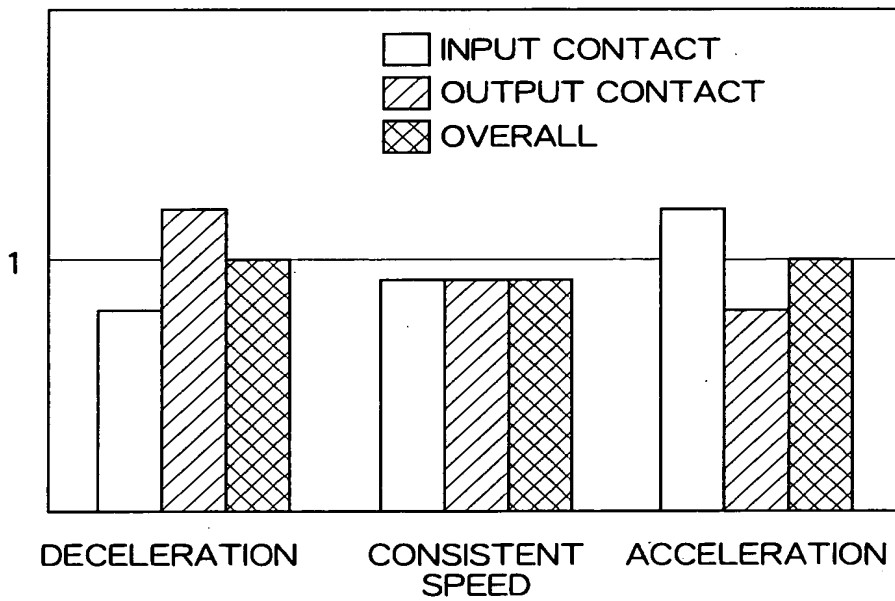
COMPARING WITH CIRCULAR ARC  
PERFORMANCE



SPEED CHANGING STATE  
OPTIMIZED AT NEUTRAL POSITION (B)

Fig.17

COMPARING WITH CIRCULAR ARC  
PERFORMANCE



SPEED CHANGING STATE  
OPTIMIZED AT OUTERMOST POSITION(C)

Fig.18

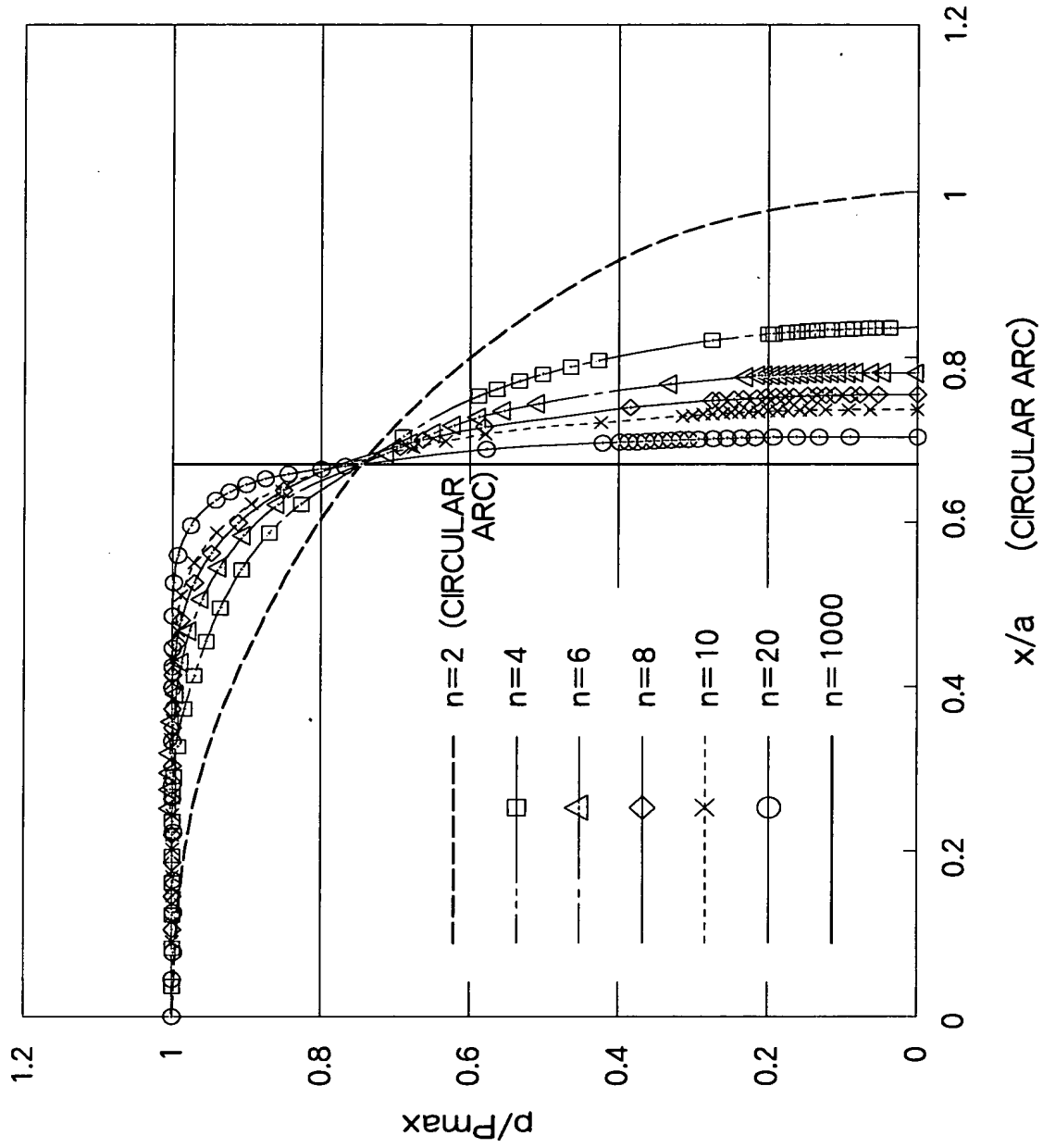


Fig.19

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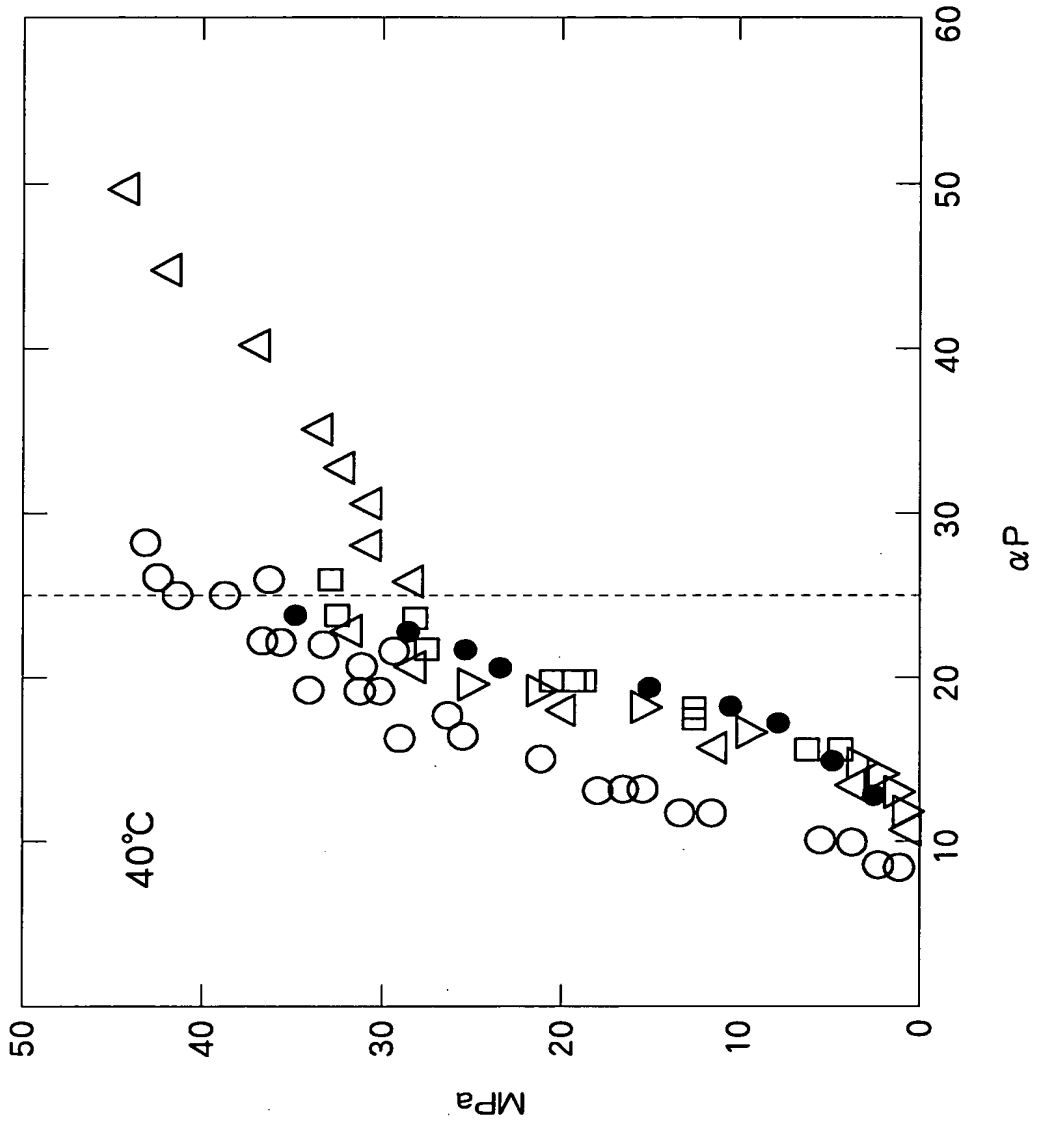


Fig.20

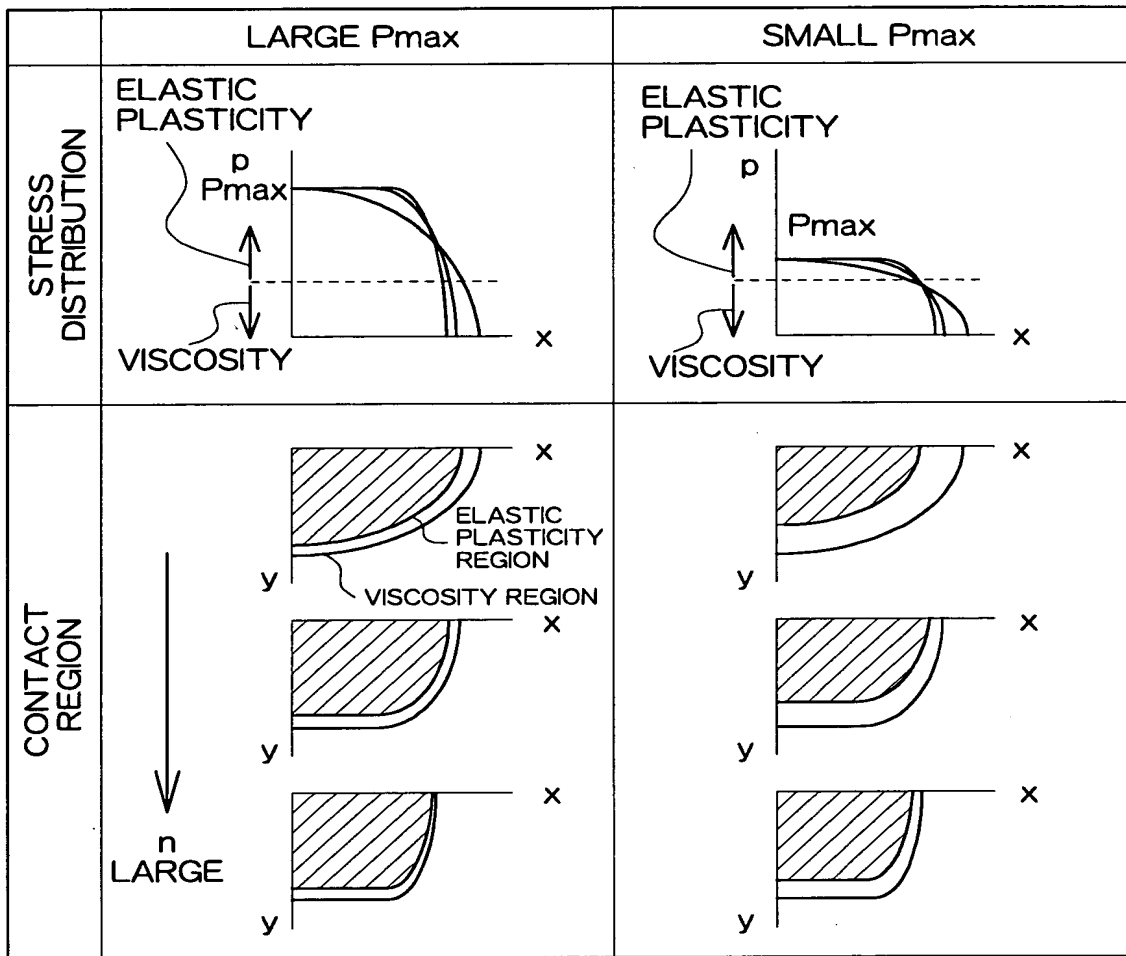


Fig.21

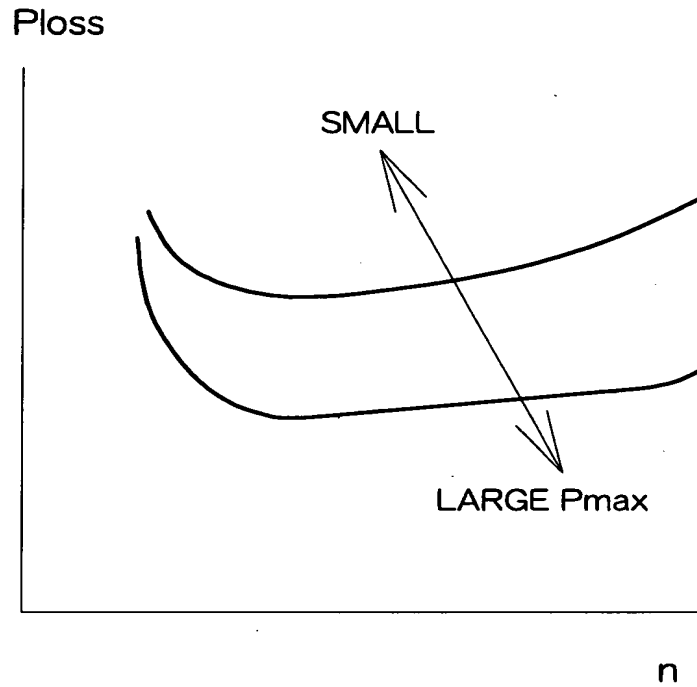


Fig.22

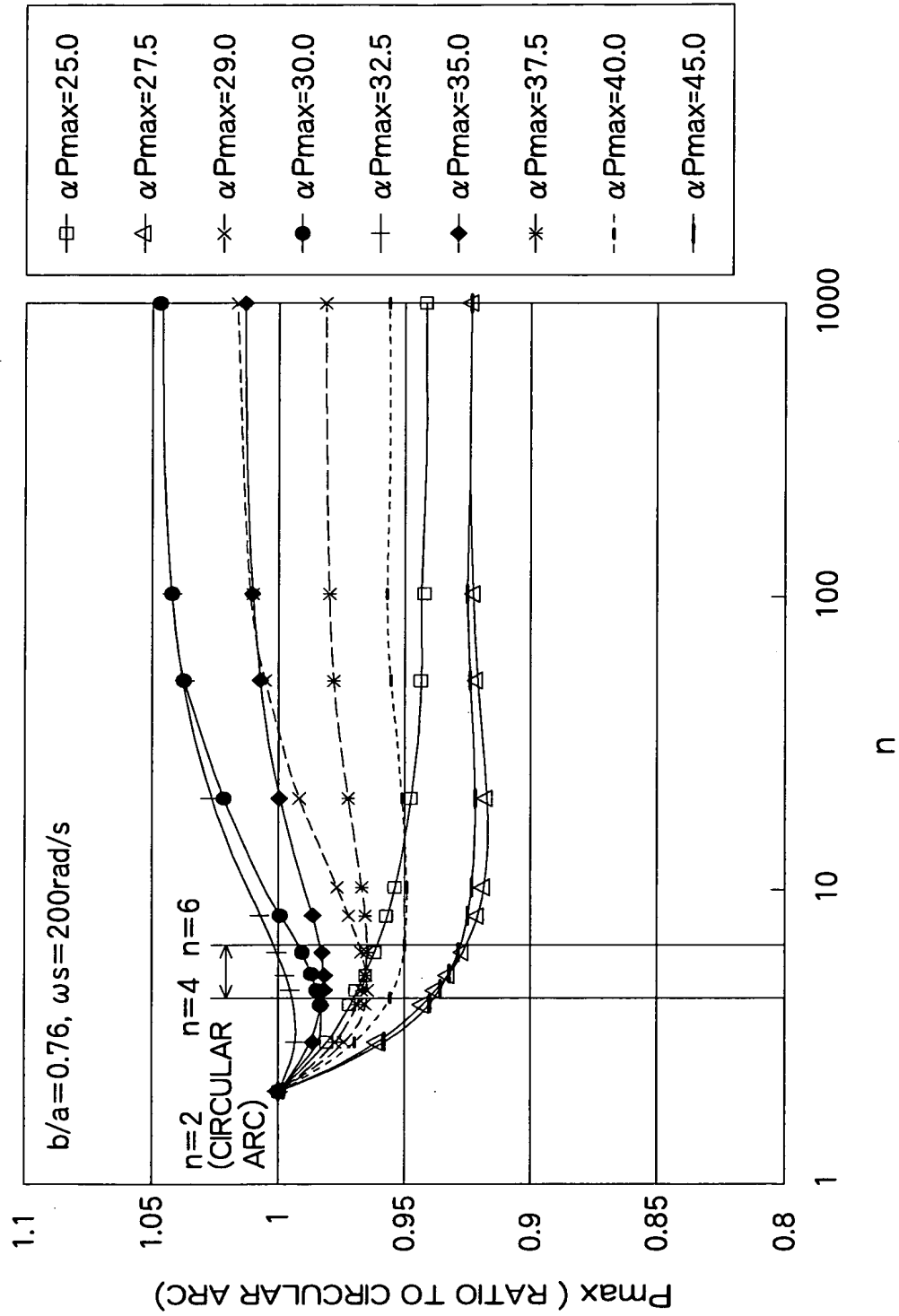


Fig.23



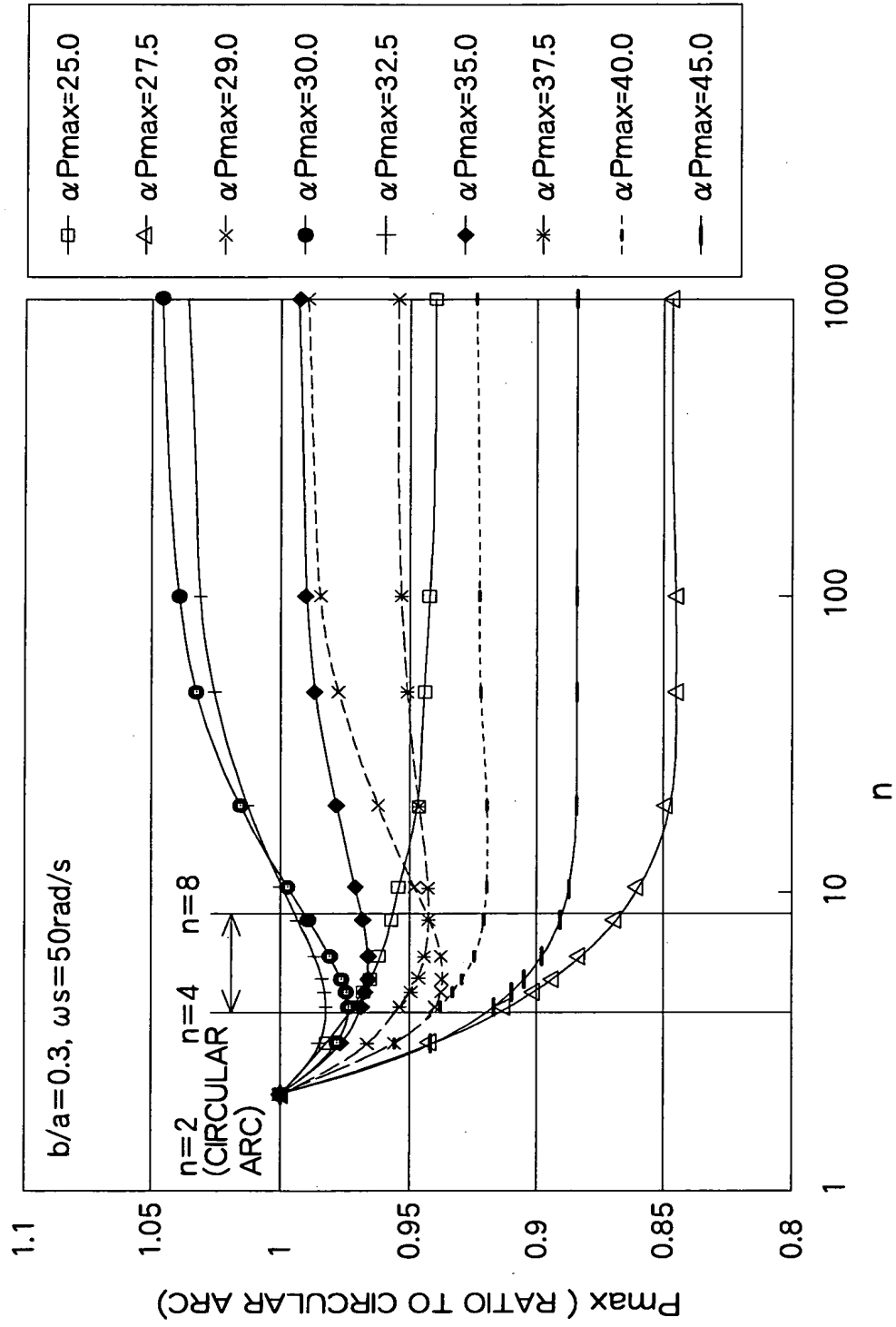


Fig.24

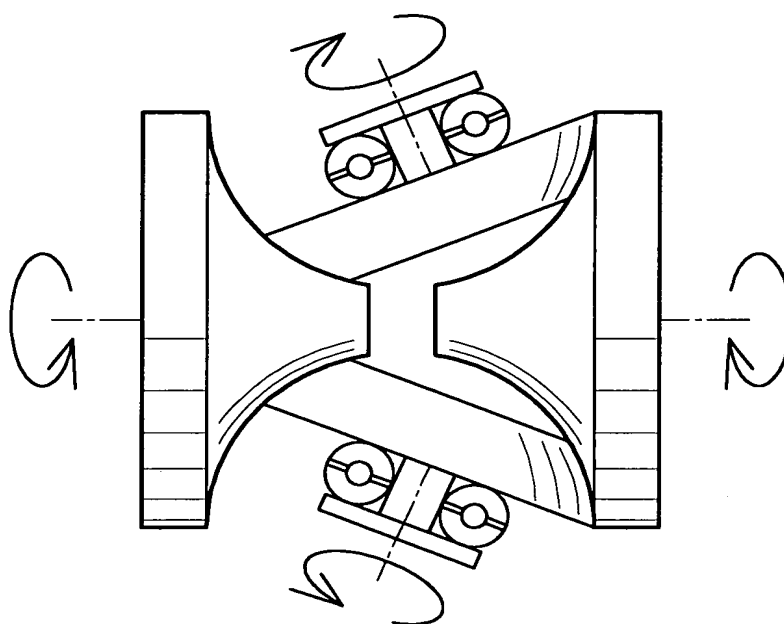


Fig.25

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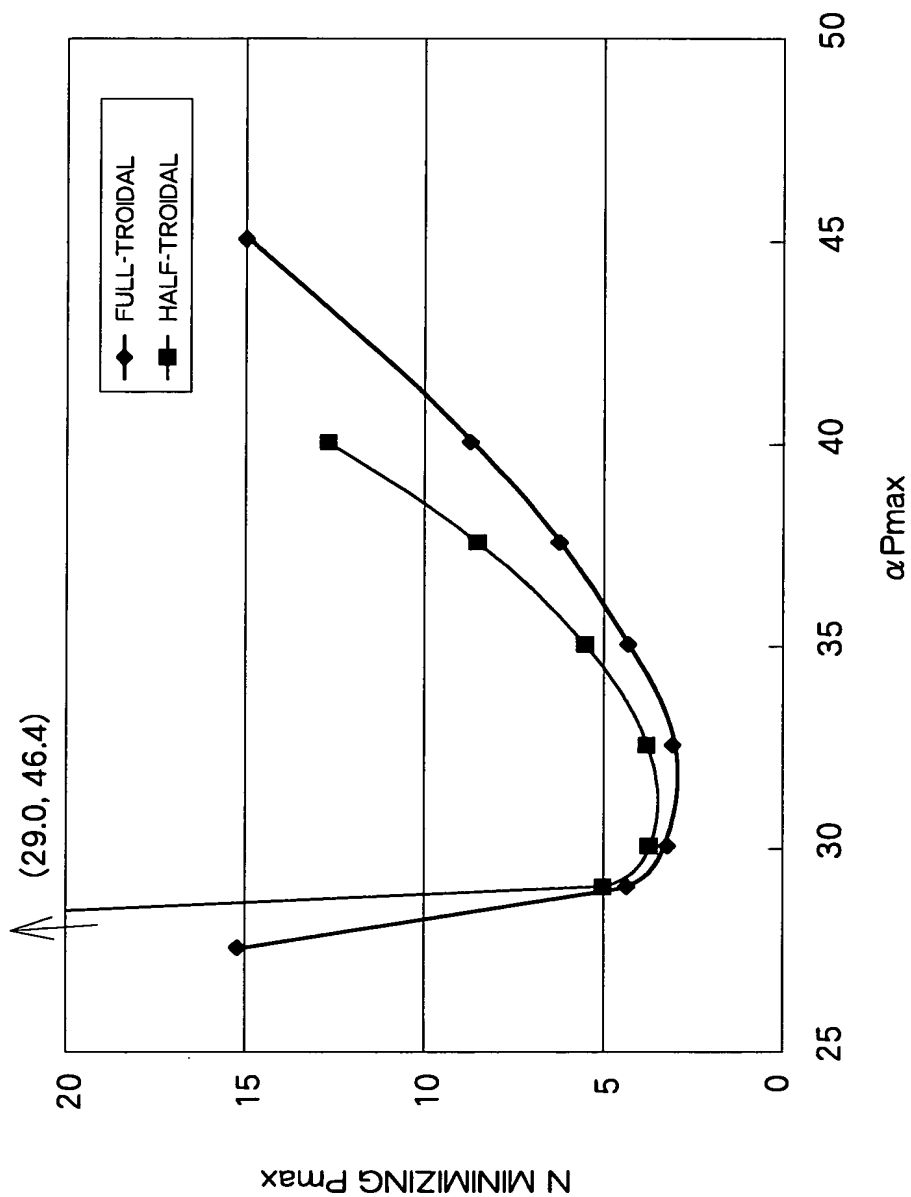
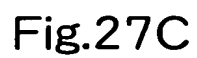
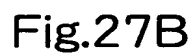
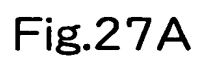


Fig.26



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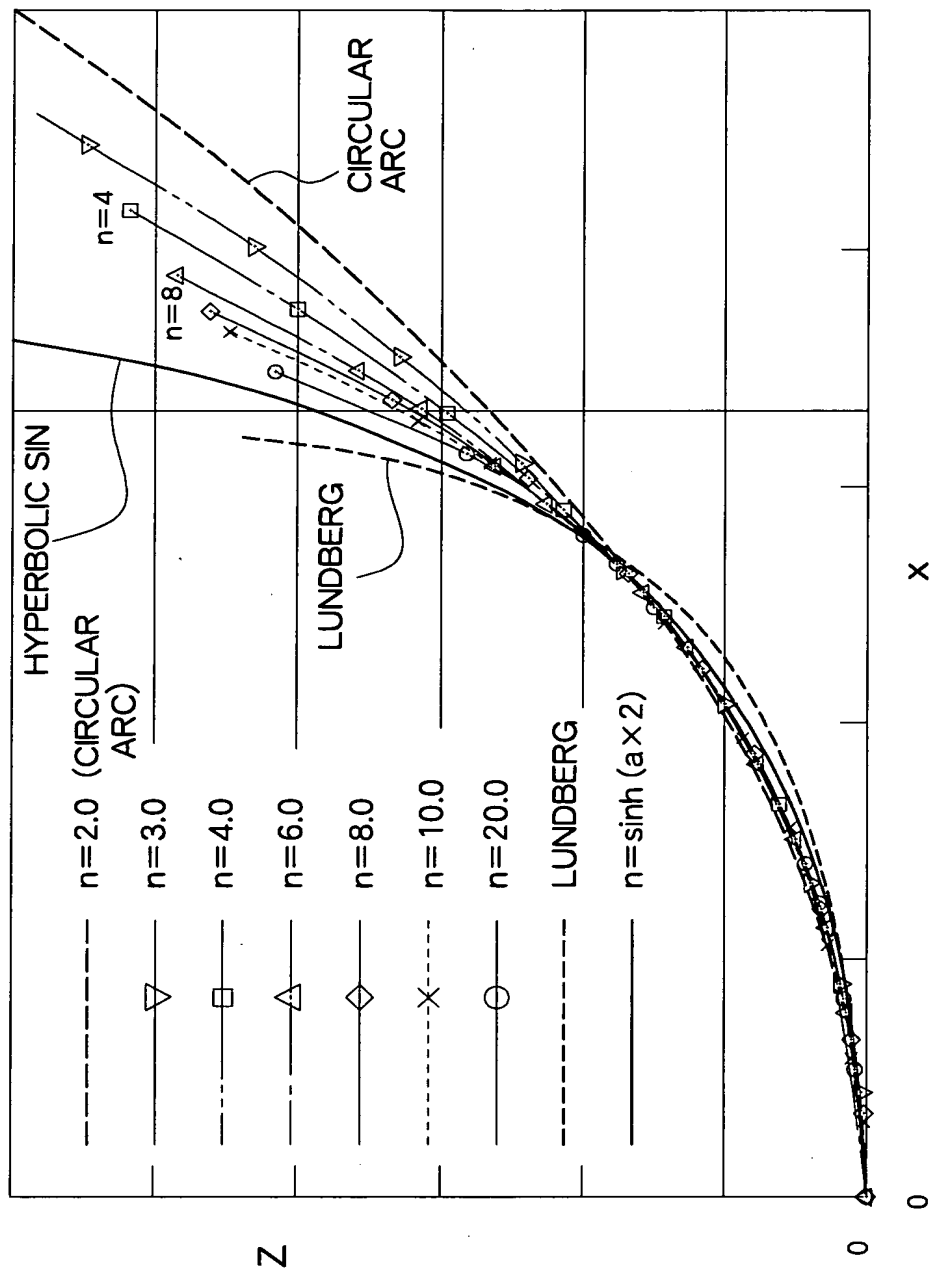


Fig.28